

Mission requirements and satellite overview

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Dual concept – Users need

PLEIADES

Defence needs

✓ Fulfil the Defence needs on confidentiality and security

Civilian needs

- ✓ Fulfillment of the different needs of institutional users (National and International, i.e. GMES) scientific users commercial users
- ✓ Large quantity of civilian images to be acquired
- ✓ Open access to the system via public networks (internet)

Common needs

Priority: Very urgent requests have highest priority

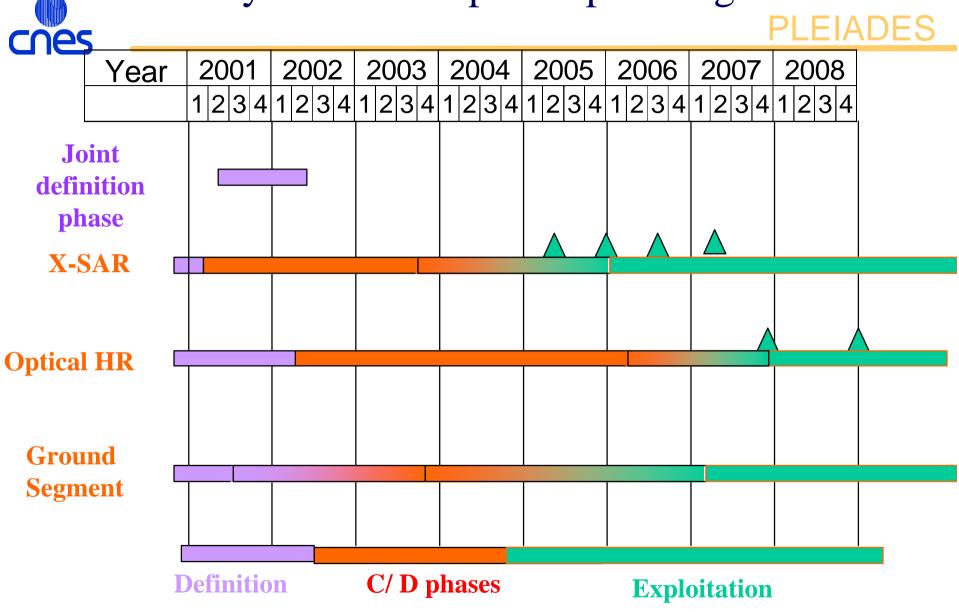
High Reactivity: Acquisition and delivery delays should be very short



Operational Modes requirements

- Three operational modes are specified in the mission requirement document:
 - Routine mode
 - daily basis mission planning, 7 days a week
 - Crisis mode
 - 12 hours mission planning, absolute priority on crisis area
 - Very urgent request
 - Reduce the programming delay to allow late introduction of energency requests (PLEIADES will be used in GMES frame)
- Great care is taken to design a global system with high reactivity, reducing data acquisition and data dissemination delays.

Dual System development planning

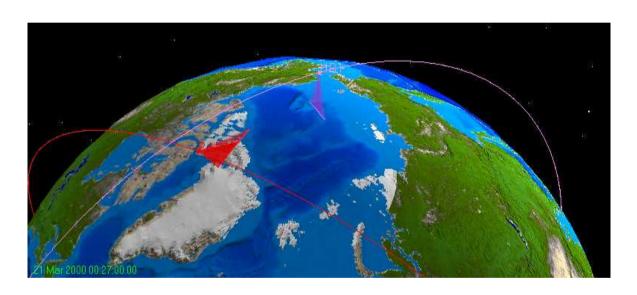




Pleiades main characteristics



- 2 satellites phased at 180° (revisit time 24 hours)
- phased sun-synchronous 14+15/26
- altitude 695 km
- equator cross time around 10h30



- Radar

- 4 satellites phased at 90° (revisit time 12 hours)
- phased sun-synchronous 14+13/16
- altitude 620 km
- equator cross time around 6h00



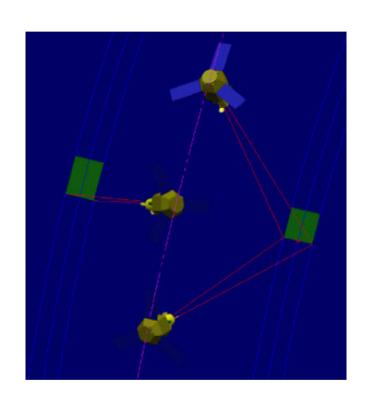
PHR main requirements

- Main specifications
 - revisit time less than 24 hours need of 2 HR satellites
 - reference daily capacity: 250 images per satellite
- performance domain : 30° half-angle cone
- instrument:
 - 20 km nadir swath
 - panchromatic résolution < 1.00 m in the performances domain (0.70 m at nadir)
 - 4 spectral bands:
 - resolution : 4 times PAN resolution
 - SPOT bands + blue band (=> natural color)



PHR main requirements

- Agility
 - roll and pitch:
 - 5° in less than 8 seconds
 - 10° in less than 10 seconds
 - 60° in less than 25 seconds
 - → stereo and tri-stereo imaging capabilities
 - → single pass multi-bands mosaiking
- Product localization on reference ellipsoid with a "perfect" DTM:
 - 12 m (circular error with 90% of probability)
 - 24 m (circular error with 99,7% of probability)





Mission performances

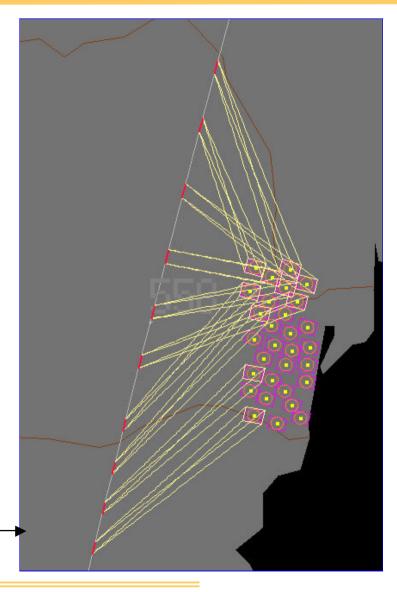
PLEIADES

"Instantaneous" capabilities:

Crisis area:

- Over an area of interest of 100 x
 200 km².
- 11 targets in one pass for 20° viewing angle authorised access
- 16 targets in one pass for 30° viewing angle authorised access

Example of 20° viewing angle in roll and pitch combined (10 images)





Mission performances

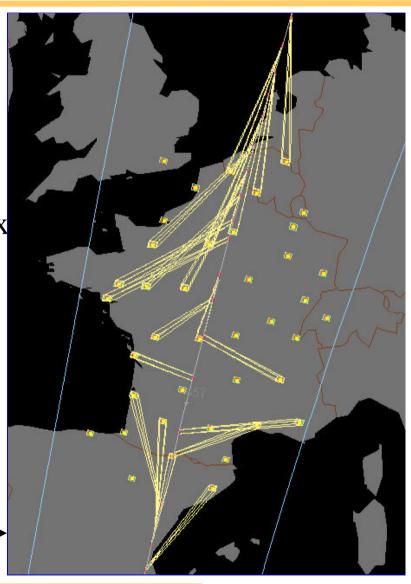
PLEIADES

"Instantaneous" capabilities:

Commercial mission over Europe:

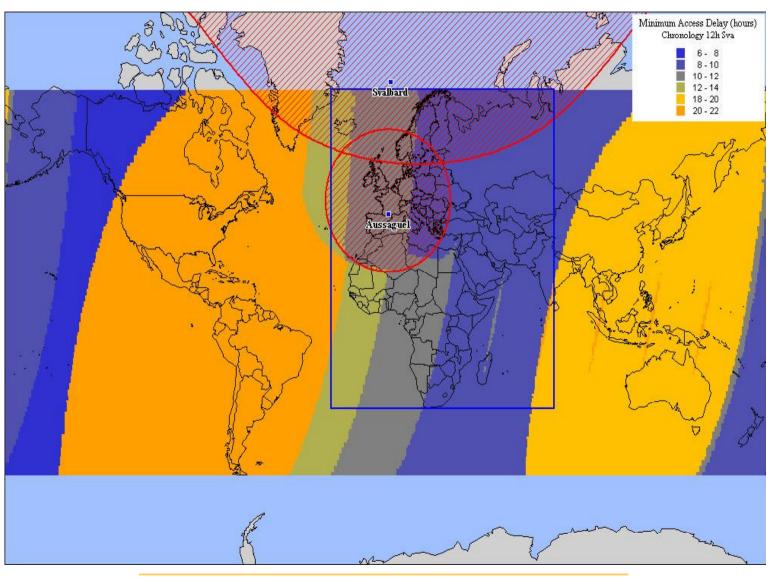
- Over an area of interest of 1000 x 1000 km².
 - 19 targets in one pass for 20° viewing angle authorised access
 - 21 targets in one pass for 30° viewing angle authorised access

Example of 30° viewing angle in roll and pitch combined (20 images)



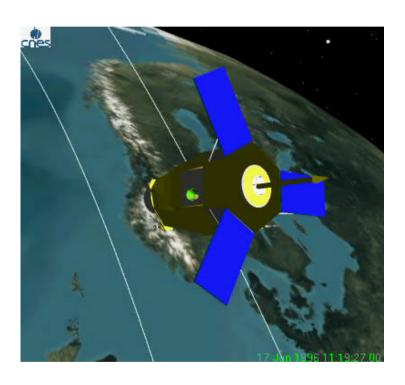


Access Delay Performances





Mission performances





The Pléiades High Resolution optical satellite

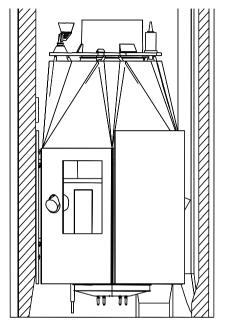


Pleiades HR Satellite A new concept for European Earth Observation

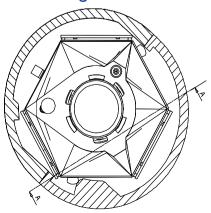
- Pléiades HR satellite
 - New generation of sub-metric Optical Earth Observation minisatellite ready for 2007
 - Including new generation technologies for the satellite allowing high system performances
- Industrial organization highlights
 - Cnes is in charge of the system development
 - Astrium is prime contractor for the satellite and the bus
 - Alcatel is prime contractor for the optical instrument



Satellite architecture and design External configuration



Under Rockot fairing configuration



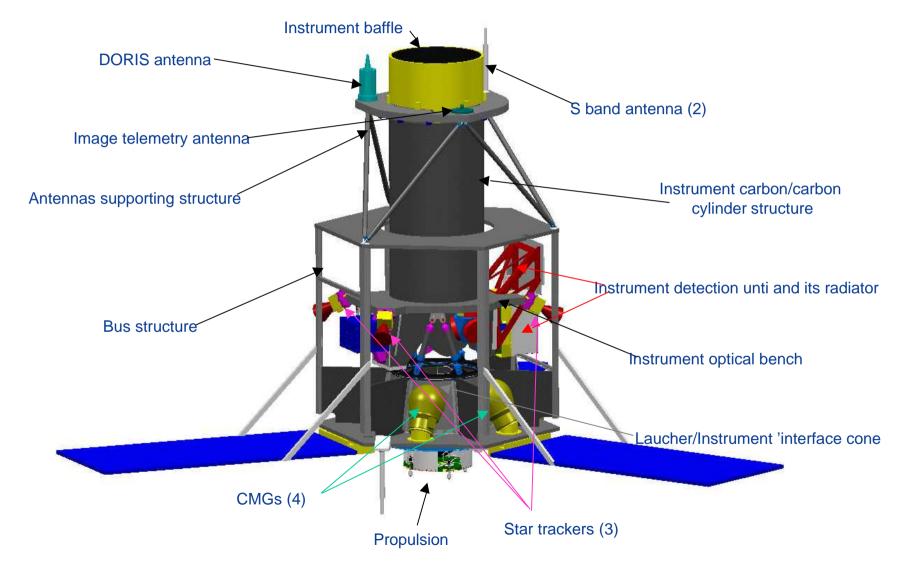
- Low mass (<1000 kg) and high compacity allowing small launchers compatibility
 - Rockot, Soyouz, Vega, ...
- High performances optimized design
 - For agility
 - Vertical instrument inside the bus for volume and inertia minimization
 - High stiffness fixed small solar arrays (three panels)
 - For Image Quality
 - Instrument mounted on the launcher interface cone with isostatic truss
 - Fine sensor heads mounted on the instrument for maximum geometrical quality accuracy



Satellite In-flight configuration

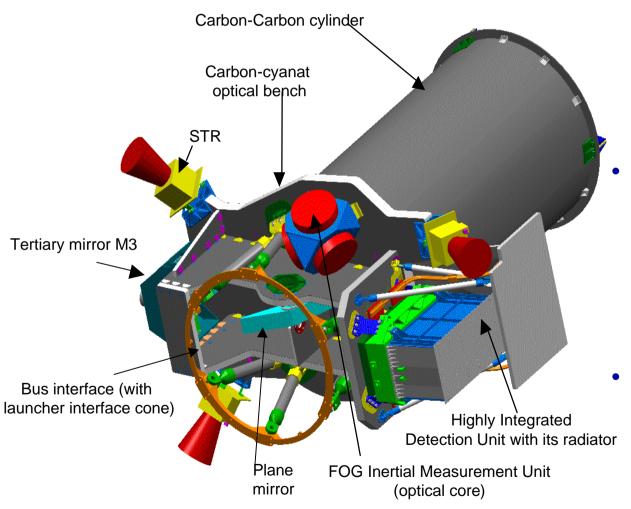


Satellite architecture Instrument accomodation into the bus





Instrument Design Overall architecture

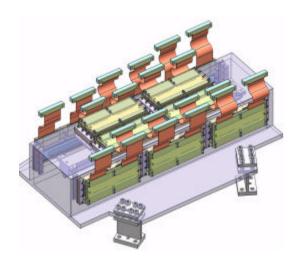


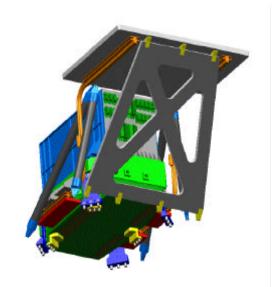
- Optical design based on Korsch solution
 - Focal length of 12.9 m
 - Primary mirror with 650 mm diameter
 - Three zerodur mirrors plus one plane mirror
 - Mechanical Design
 - Central plane structure supporting all telescope elements
 - M1, M3, plane mirror, fine sensors
 - Carbon-Carbon cylinder for M1-M2 structure
 - Thermal design
 - Passive cooling plus heaters
 - Cold tube M1-M2
 - Decoupled detection unit with heat pipes and dedicated radiator



Instrument Design Focal plane and Detection Unit

- Detection Unit Focal plane
 - 5 TDI Panchromatic detectors of 6000 pixels each with lateral anti -blooming
 - 20 to 50 lines of integration
 - 5 4-color detectors of 1500 pixels
 each
- Detection Unit proximity electronics
 - 5 PAN and 3 XS in dedicated PCB's housed behind the focal plane providing analogical video processing and A/D conversion
 - Pan detector output : 58 Mpixel/s
 - Total Pan output : 3.5 Gbit/s
 - Total XS output : 0.875 Gbits/s







Bus DesignPayload Data Handling

- Compression Unit based on wavelet algorithm ASICs with mean ratio of 2 bits/pixel in panchromatic band and 2.5 bits/pixel in XS bands
 - Input rate of ≈ 4.5 Gbit/s
- Mass Memory Unit of 600 Gbits (EOL) storage capacity
 - 1.5 Gbit/s max input rate,
 - auxiliary data (satellite attitude and position) through 1553,
 - three 155 Mbit/s outputs
- Image Telemetry
 - Three parallel trellis-coded 8-PSK modulators in X band coupled to travelling waves tubes power amplifiers (TWTA)
 - One omni-directionnal 64° conical aperture antenna

